



Spur and Gear Design With Minimized Interference and Improve Contact Ratio

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Abstract: The design of spur gears plays a important role in efficient power transmission systems, where interference between mating teeth can lead to noise, vibration, wear, and eventual failure. This review paper focuses on various methods used to minimize interference in spur gear design and improve overall performance. Interference mainly occurs when the gear teeth are improperly designed or when the number of teeth is too low, leading to undercutting and weak tooth profiles. To address this issue, several design modifications are discussed, including increasing the pressure angle, using stub teeth, applying profile shifting, and optimizing the number of teeth. Increasing the pressure angle helps in reducing interference by allowing fewer teeth without undercutting and improving tooth strength. Stub teeth reduce the addendum, thereby minimizing the chances of interference at the tooth tip. Profile modification techniques such as tip relief are also effective in reducing contact stresses and improving meshing conditions. Additionally, advancements in computational tools like finite element analysis have enabled better evaluation of stress distribution and tooth behavior under load. The paper reviews existing research and highlights the importance of selecting appropriate design parameters for achieving interference-free operation. Overall, minimizing interference not only enhances gear life but also ensures smooth, quiet, and efficient performance in mechanical systems.

Keywords: Spur Gear, Gear Interference, Contact Ratio, Undercutting, Profile Shifting, Pressure Angle, Addendum Modification, Gear Geometry, Involute Profile, Transmission Efficiency, Noise Reduction, Gear Tooth Strength.



I. INTRODUCTION

Among common mechanical parts, spur gears stand out in transferring motion across parallel axes because they're straightforward to produce, operate efficiently, and rely on uncomplicated geometry. Yet problems arise during operation if tooth profiles interact beyond designed points - this mismatch, known as interference, disrupts alignment. Such unintended contact tends to accelerate surface degradation, generate unwanted sound, and compromise structural integrity over time. Preventing these overlaps becomes critical when aiming for consistent torque transfer, longer service life, and stable function under load. This review paper focuses on various design approaches and analytical methods used to reduce interference in spur gears. It examines the influence of key parameters such as tooth profile, pressure angle, module, addendum modification, and number of teeth on interference conditions. The paper also discusses modern optimization techniques and computational methods that help achieve better load distribution and higher contact ratios.

II. LITERATURE REVIEW

Osakue and Anetor (2016) focused on improving spur gear performance and reliability through refined design approaches. They emphasized balancing efficiency and durability rather than relying only on traditional design methods. Key design parameters such as tooth number, module, and pressure angle were analyzed for overall system performance. The study highlighted the importance of proper load distribution and contact ratio for smooth operation. Small modifications in tooth profile and tip design were shown to significantly improve gear behavior under load. Optimization techniques were recommended to enhance performance, reduce stress, and lower manufacturing cost. Their work provides practical guidelines for designing stable, efficient, and long-lasting spur gear systems. [1]. Through experimentation, Yilmaz and Eyercioglu (2018) explored how concave preforms affect spur gear forging, aiming to refine material movement while lowering flaws. Instead of standard shapes, these modified blanks helped achieve forms nearer to the intended gear outline - cutting down later machining steps. Simulations based on Finite Element Analysis tracked how metal deformed, where stresses built up, and whether cavities filled completely during compression. Because the inward curve guided flow more effectively, teeth formed with fewer issues like gaps or folded layers. When tested, this approach delivered sharper profiles and tighter dimensions than traditional designs offered. What made it work well was how much less force and power were needed during forging. Tests lined up closely with what simulations had predicted. Shaping the initial piece correctly turned out to matter a lot - especially for spreading internal forces evenly and preventing weak spots. Quality went up at the same time expenses dropped slightly. Starting gears from a curved blank appears to be one solid way forward when building them fast without losing strength [2]. Looking at spur gears, Shanmugasundaram, Kumaresan, and Karthikeyan in 2011 compared how different pressure angles affect stress and interference through FEA using ANSYS. With consistent load applied across models, gears were tested at 14.5°, 20°, and 25° pressure angles. Higher values shifted the stress patterns favorably - clearance between teeth increased, lowering chances of unwanted contact. Though all versions behaved differently, the design with 25° stood out by showing minimal bending and contact stresses around the base of the gear tooth. Because of this shift in load handling, potential for damage dropped noticeably within that configuration. Despite better results, there was a downside: the contact ratio dropped roughly 12%, which made power transfer slightly rougher. Smoothness and strength reached a middle ground with a 20° pressure angle. Choosing the right pressure angle matters - especially when balancing clearance needs against how well surfaces interact. Using finite element analysis helped reveal how changes in design affect gear behavior. In each case, simulation offered clear insight into performance shifts [3]. Starting with uneven tooth shapes, Deng, Hua, and Han in 2015 explored how altering spur gear design affects durability and function. Instead of matching both sides, they applied separate pressure angles to the driving and non-driving flanks for better efficiency. Their approach involved building a precise geometric framework to simulate engagement behavior between teeth. Modifications to the tooth outline were then tested within this system. Findings revealed stronger resistance to bending stress on the



active surface, even as contact quality stayed within usable limits. One way to lower stress hotspots involves changing the gear profile shape. This shift helps spread forces more evenly across the surface. Instead of simply adding features, adjusting form alters how contact moves during operation. Evidence from computer models supports these adjustments as practical solutions. When geometry is tailored correctly, parts interact with less conflict. Efficiency gains appear through smoother power transfer between components. Durability rises when uneven wear gets limited by smart shaping. Failures at the tooth level become less likely under heavy loads. Asymmetry in spur gears offers a workable path forward for demanding uses. Results show better function without needing new materials or complex systems [4]. Starting with Radzevich's 2016 work, the update breathes new life into Dudley's classic guide on gear design and manufacturing. Though rooted in theory, it stays grounded in real-world application throughout. Because depth matters here, coverage spans both foundational principles and hands-on techniques. Instead of skipping ahead, each section builds carefully on prior knowledge. While older editions laid groundwork, this version refines clarity and precision. Since gears remain central to mechanical systems, relevance holds firm across industries. Following technical evolution, updates reflect current methods without losing original intent. A close look at how gears are shaped begins with their curved teeth, formed by an involute pattern. Motion transfer between these parts comes down to precise interactions studied under gear kinematics. What matters most is the way surfaces roll against each other without slipping. These ideas form a base for understanding mechanical transmission systems. Interference and undercutting receive close attention here. Ways to steer clear of these issues follow, though not always in expected sequence. Solutions appear throughout, linked by logic rather than repetition. Each approach unfolds separately, yet connects where needed. Clarity comes through variation, not redundancy. Starting off, the guide presents equations used to figure out how few teeth a gear can have without causing overlap issues. One key aspect stands out: tweaking addendums shapes how gears perform. Profile adjustments bring noticeable differences too - small changes affect function directly. Shifting geometry alters contact patterns across teeth surfaces. Design gains come through precise modifications rather than broad rules. Each alteration impacts meshing behavior in unique ways. Bending stress appears early in the discussion, followed by contact stress examined through practical examples. Safety during gear function shapes how both topics are explored throughout the chapters. Choosing materials like steel, cast iron, or various alloys for gears gets a thorough breakdown. While strength matters, durability under stress shapes each decision. One factor - wear resistance - influences long-term performance more than initial cost. Temperature changes affect metal behavior, so environment guides picks. Sometimes lighter alloys work better, even if less tough. What works in machinery may fail in vehicles. Each option carries trade-offs that show up over time. From casting to grinding, methods like forging and hobbing appear across different production techniques. Processes including these shape materials in distinct industrial settings. Improving gear longevity involves techniques such as carburizing, which alters surface properties. Hardening processes follow, adding strength through controlled cooling. One method builds on another, shaping durability from thermal manipulation. Life span increases when layers resist wear. Changes occur beneath the surface, unseen but effective. Performance shifts under repeated stress. Each step targets failure points before they arise. Another concern tackled is unwanted sound and shaking in gears, since these impact how well they work and last over time. Besides surface wear, engineers also study cracks that grow slowly under stress. One kind of damage appears as tiny craters forming on metal faces. Another shows up when rough spots begin to tear material away. Over time repeated loads cause internal weaknesses too. Design rules from groups like AGMA and ISO help shape real-world engineering choices. While some methods differ, both influence how machines are built. Their guidelines appear often in everyday planning. Because they offer tested approaches, engineers rely on them regularly. Though not always mandatory, their presence is common across industries. Where precision matters, these frameworks tend to show up [5]. A single crack at the base of a gear tooth was examined by Chen and Shao (2011), tracking how it spreads across width and into depth. Their focus lay on motion patterns in spur gears as damage progresses gradually through material layers. Instead of isolated points, growth in two directions shaped their analysis. Movement changes emerged alongside structural weakening. What began small widened and deepened under repeated load cycles. A simulation of how cracks spread was built using math,



showing changes in gear vibrations as a result. Though crack behavior drives vibration shifts, the approach captures both elements together through equations shaped by observed patterns. Crack growth weakens gear rigidity, altering how the system reacts dynamically. This study supports identifying problems early in gear systems while tracking their state over time. Monitoring performance becomes more reliable when signs appear before failure risks grow. Early warnings help maintain operations without sudden breakdowns occurring later on. Gear health improves through consistent observation using these methods. Detection at initial stages makes a difference in how long components last under stress [6]. Improving surface quality in skived face gears became the focus when Tang and colleagues introduced their phase-shifted feed path approach in 2026. Surface roughness produced in power skiving is the main subject of this research. A slight delay was added to the movement of the tool, shifting its pattern on purpose. This change spread the marks left by cutting across the surface more evenly. Instead of lining up, the traces now appeared scattered. The result came from timing adjustments made during operation. Uniformity improved because each pass did not repeat the exact previous position. Surface flaws drop sharply when using this approach, resulting in smoother gear teeth. The technique reshapes imperfections gradually, leaving a refined outcome across each tooth face. By focusing on precision early, unwanted roughness fades through consistent contact adjustments. By improving precision, the method speeds up production while keeping steps unchanged. This study helps enhance how gears perform, last longer, reduce sound issues - especially where accuracy matters most [7]. Turan and Salman (2024) analyzed tooth tip interference and stress distribution in high contact ratio spur gear pairs. They used an optimized design tool to improve gear geometry and reduce interference problems. The study shows that high contact ratio gears can experience tip interference if not properly designed. Optimization helps adjust parameters like addendum, pressure angle, and tooth profile. Results indicate a reduction in stress concentration when interference is minimized. The improved design increases load-carrying capacity and smoothness of operation. This work is important for designing efficient spur gears with better durability and reduced failure risk [8]. Barot and Barot (2017) reviewed various optimization methods used in gear design. The paper discusses techniques to improve gear performance, efficiency, and durability. It highlights methods such as weight optimization, stress reduction, and material selection [9]. The paper focuses on the design and analysis of composite spur gears using the Finite Element Method (FEM). It compares traditional steel gears with composite materials to evaluate performance improvements. Lighter yet strong performance through composite materials, as studies confirm their ability to hold structural demands without adding mass. Under working conditions, the research examines how stress spreads throughout the structure. Deformation patterns emerge as forces shift across materials. Load-bearing performance gets evaluated through observed responses. Where pressure builds, shape changes follow closely behind. Capacity limits become clear when systems face real-world demands. Some areas of composite gears show reduced stress buildup when placed beside metallic ones, according to findings. Still, findings suggest composite spur gears offer reduced weight alongside strong performance when set against traditional designs. Though uncommon, these materials hold promise where efficiency matters most in gear systems. Different optimization approaches like analytical, numerical, and computational methods are compared. The study also considers parameters like tooth profile, contact ratio, and load distribution. Results show that optimization helps in reducing failure, noise, and manufacturing cost. This review is useful for selecting suitable methods to design efficient and reliable gear systems [10].

III. RESEARCH GAP

Even though much work has been done on spur gear design, key issues still go unanswered. Earlier efforts usually tackle interference prevention and contact performance separately, instead of balancing them together when loads, speeds, or materials change. Many models rely on perfect tooth shapes, created through theory or simulation, overlooking how small production flaws - like uneven profiles, spacing errors, or wobbling - affect where interference actually occurs. Studies focusing on adjusting tooth shape for gears with fewer than twelve



teeth, common now in tight spaces like robot joints or drone motors, rarely include physical tests. Heat generated at high speeds also plays a role, especially in plastic or light composite gears, yet its impact on triggering interference is poorly explored so far. Though classical gradient-driven approaches lead current research, techniques like Genetic Algorithms, Particle Swarm Optimization, or the Grey Wolf Optimizer see little use in solving combined interference and contact ratio challenges. Instead of isolated treatments, coupling lubricant film depth with real-world interference limits demands blended tribological and motion-based modeling - an effort rarely seen. Rather than focusing only on fixed operational states, examining how sudden load shifts, variable speeds, or impact forces trigger interference could reveal deeper insights. Building a cohesive framework that tackles multiple goals at once may enhance how dependable, effective, even usable spur gears become within today's machines .

IV. METHODOLOGY

In this review paper, information is collected from books, journals, and research articles on spur gear design. Different studies related to gear interference and its effects are carefully reviewed. The main causes of interference in spur gears are identified and explained. Various methods to minimize interference, such as proper tooth profile and pressure angle selection, are studied. Standard design formulas and conditions to avoid interference are compared from different sources. Previous research findings are analyzed to understand the best design practices. Important parameters like module, number of teeth, and addendum are discussed.

V. RESULT AND DISCUSSION

HOW TO MINIMIZE INTERFERENCE IN SPUR GEARS — DETAILED METHODS

Method 1: Increase the Number of Teeth on the Pinion

This is the most fundamental and straightforward method. Since interference occurs primarily when the pinion has too few teeth, simply increasing the tooth count eliminates the problem at the source. As the number of teeth increases, the gear tooth profile approaches a rack profile (infinite gear), and the involute curve extends more gently, eliminating the possibility of the addendum circle extending beyond the base circle interference point. Increasing the number of teeth on a gear is one of the most fundamental methods to avoid interference. Interference typically occurs when the number of teeth on the pinion is too small, causing the involute profile to intersect with the non-involute portion of the mating gear tooth. By increasing the number of teeth, the base circle diameter increases, which ensures proper involute action throughout the contact region. This reduces the chances of undercutting and tooth tip interference. Moreover, a higher number of teeth improves the contact ratio, meaning more than one pair of teeth share the load at a time, resulting in smoother transmission and reduced stress concentration. However, increasing the number of teeth may increase the overall size and weight of the gear system, which may not be suitable for compact applications. Therefore, an optimal balance between tooth number, size, and performance must be maintained [8].

Mathematical Basis: The minimum tooth number for interference avoidance is: $N = 2k/(\sin^2\phi)$ for meshing with a rack, or $N = 2k/(1 + (1+2i)\sin^2\phi \times (1/i))$ for a finite gear ratio i . With $k=1$ (full-depth teeth) and $\phi=20^\circ$: $N_{min} = 17$ teeth (rack mesh) and as low as 14 for gear ratio 3:1. (N = Number of Teeth on Pinion , N_{min} =Minimum Number of Teeth , k = Addendum Coefficient , ϕ = Pressure Angle , $\sin^2\phi$ = Square of sine of pressure angle)



Practical Implementation: In most industrial gear designs, using $N_1 \geq 17$ for standard 20° gears eliminates interference entirely. For high-ratio gearboxes where small pinions are required ($N_1 < 17$), other methods below must be combined.

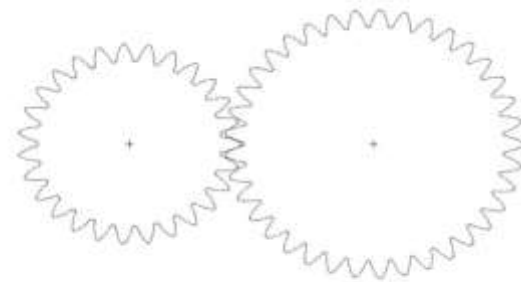


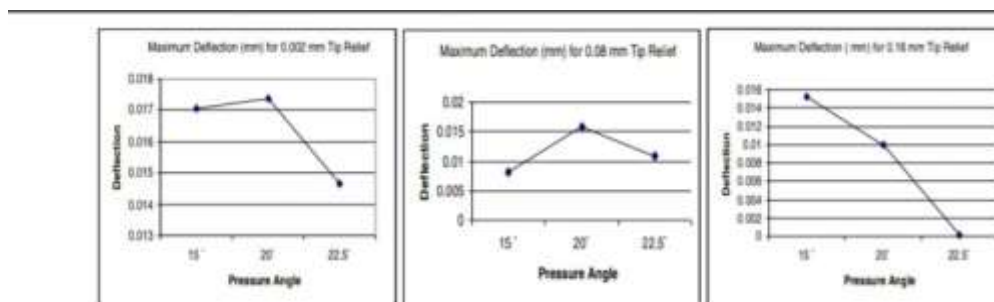
Figure : Standard gear pair with 27 and 37 teeth, 2.5 mm module, and 25 degrees pressure angle.

Method 2: Increase the Pressure Angle

Increasing the pressure angle from the older 14.5° standard to 20° (and in some applications to 22.5° or 25°) is one of the most effective methods of reducing interference. A larger pressure angle shortens the addendum relative to the line of action, meaning the addendum circle is less likely to extend beyond the interference point. The base circle is also larger for the same pitch circle, meaning more of the tooth profile is involute. Increasing the pressure angle is an effective method to reduce interference in gears. A higher pressure angle decreases the minimum number of teeth required, thus avoiding undercutting. This allows compact gear design with fewer teeth. It also increases the thickness of the tooth at the base, making it stronger and more resistant to bending failure. The curvature of the tooth profile improves, reducing sliding velocity and wear. As a result, gear life increases. However, increasing pressure angle also increases radial forces acting on bearings. It may reduce the contact ratio, leading to less smooth operation. Therefore, a balance is required while selecting the pressure angle. Common values used are 20° and 22.5° [3].

Mathematical Basis: The maximum possible length of approach (before interference) is: $L = r_1 \cdot \sin(\phi)$, where r_1 is the pitch radius of the pinion. For standard addendum $a = m$, and pitch radius $r_1 = mN_1/2$: $L = (mN_1/2) \cdot \sin(\phi)$. Since the gear addendum on the line of action = m (for standard gears), interference is avoided when: $m \leq (mN_1/2) \cdot \sin^2(\phi)$, i.e., $N_1 \geq 2/\sin^2(\phi)$. For $\phi=14.5^\circ$: $N_{\min} \approx 32$; for $\phi=20^\circ$: $N_{\min} \approx 17$; for $\phi=25^\circ$: $N_{\min} \approx 11$. (m = module, N_1 = number of teeth on pinion, N_{\min} = Min number of teeth on pinion)

Practical Recommendation: For standard applications, 20° is optimal. For compact high-ratio drives with small pinions, 22.5° or 25° may be used with acceptance of slightly lower contact ratio, compensated by wider tooth face width.



Deflection comparison graph.

Method 3: Using Stub Teeth



Stub teeth are gear teeth with a reduced addendum compared to the full-depth standard. In the American stub tooth system, the addendum is 0.8m and the dedendum is 1.0m (vs. 1.0m and 1.25m for standard full-depth teeth).

Principle: By reducing the addendum height, the tip of each tooth is kept closer to the pitch circle and further from the interference point. Since interference occurs when the tooth tip extends beyond the interference point, reducing the tip height directly reduces interference risk.

Trade-offs: Stub teeth have a shorter contact path, which reduces the contact ratio (typically by 0.1 to 0.2 compared to full-depth teeth). They also have less tooth overlap, which can reduce load-sharing benefits. However, stub teeth have thicker flanks, which improves bending strength.



Method 4: Helical Gear Conversion

While this paper focuses on spur gears, it is noteworthy that converting a spur gear application to a helical gear design is an effective way to eliminate interference problems while simultaneously improving contact ratio.

Principle: In helical gears, the effective normal pressure angle is larger than the transverse pressure angle, and The total contact ratio is: $CRTOTAL = CR PROFILE + CRAxIAL$. This makes it much easier to achieve contact ratios above 2.0 while maintaining low total profile axial transverse interference.

Application: For spur gear pairs where interference cannot be adequately controlled by profile shifting alone (e.g., very high gear ratios with $N1 < 8$), conversion to helical gears with a helix angle of 15–30° is recommended)



Method 5: Under-cutting and Its Controlled Use

Undercutting is the automatic removal of material from the gear tooth root during the manufacturing process when the number of teeth falls below a critical value. In a sense, undercutting is nature's own solution to interference — the cutting tool removes the material that would otherwise interfere.

Principle: When a rack cutter (hob) generates a gear with too few teeth ($N < N_{MIN}$) the tip of the rack cutter traces a path that extends below the interference point, cutting away the non-involute (trochoidal) root fillet material. The result is a gear tooth with a weakened root but no interference.

Controlled Undercutting: In precision instrument gears (N as low as 6–8 teeth), small amounts of undercutting may be deliberately accepted to achieve the required gear ratio in a compact envelope, provided bending stress levels are validated by FEA.

• Comparative Summary of Interference Minimization Methods

Method	Effectiveness	Effect on CR	Manufacturing Cost	Recommended For
1. Increase N_1	High	Improves CR	None	General design
2. Increase Pressure Angle	High	Reduces CR slightly	None	Compact high-ratio drives
3. Stub Teeth	Moderate	Reduces CR	None	Instruments, automotive
4. Helical Conversion	Very High	Greatly improves CR	Moderate	High-performance drives
5. Controlled Undercutting	Moderate	Reduces CR	None	Very compact, low-load

VI. CONCLUSION

This review concludes that minimizing interference is a critical aspect of spur gear design for achieving smooth and efficient operation. Interference leads to improper tooth engagement, resulting in higher wear, vibration, and noise. Proper gear geometry selection is essential to avoid such issues during operation. Parameters like module, pressure angle, and number of teeth strongly influence interference conditions. Reducing interference improves load distribution and enhances overall gear performance. Profile shifting is one of the most effective techniques to eliminate interference. Addendum modification also helps in maintaining proper meshing between gear teeth. Increasing the contact ratio ensures smoother transmission and reduced dynamic loads. Accurate alignment and manufacturing precision play a vital role in minimizing errors. Material selection contributes to better strength and resistance to wear. Optimization methods help in achieving a balance between strength, efficiency, and cost. Modern computational tools allow better prediction and analysis of interference problems. Simulation techniques provide insights into gear behavior under different operating conditions. Small design improvements can significantly increase gear life and reliability. Reducing stress concentration helps prevent early failure of gear teeth. Improved surface finish also contributes to smoother meshing and reduced friction. Efficient lubrication further enhances performance and reduces wear. Research shows that combining traditional design with modern optimization gives better results. A well-designed gear system ensures long-term stability and reduced maintenance requirements. Overall, minimizing interference leads to stronger, more efficient, and durable spur gear systems.



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